# Robust retrieval of material chemical states in X-ray microspectroscopy

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Abstract: X-ray microspectroscopic techniques are essential for studying morphological and 10 chemical changes in materials, providing high-resolution structural and spectroscopic information. 11 However, its practical data analysis for reliably retrieving the chemical states remains a major 12 obstacle to accelerating the fundamental understanding of materials in many research fields. In 13 this work, we propose a novel data formulation model for X-ray microspectroscopy and develop 14 a dedicated unmixing framework to solve this problem, which is robust to noise and spectral 15 variability. Moreover, this framework is not limited to analyzing two-state material chemistry, 16 making it an effective alternative to conventional and widely used methods. In addition, an 17 alternative directional multiplier method with explicit or implicit regularization is applied to 18 obtain the solution efficiently. Our framework can accurately identify and characterize chemical 19 states in complex and heterogeneous samples, even under challenging conditions such as low 20 signal-to-noise ratios and overlapping spectral features. By testing six simulated datasets, our 21 method improves the existing methods by up to 151.84% and 136.33% in terms of the peak 22 signal-to-noise ratio (PSNR) and the structural similarity index (SSIM) for the chemical phase 23 map. Extensive experimental results on simulated and real datasets demonstrate its effectiveness 24 and reliability. 25

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### 27 1. Introduction

X-ray absorption spectroscopy (XAS) is a scientific technique that utilizes X-rays to investigate 28 materials' electronic and structural properties. However, the spatial resolution of XAS is typically 29 limited to the micron or sub-micron scale, which poses a challenge when studying materials 30 with complex or heterogeneous structures. In recent years, spectroscopic full-field transmission 31 X-ray microscopy (TXM) has emerged as a novel tool for nanoscale chemical imaging, with 32 great potential in various multidisciplinary fields [1, 2]. By imaging at energy points across 33 the absorption edge of the element of interest, TXM offers both high spatial resolution and 34 chemical-specific information. Sub-50-nm resolution X-ray absorption near-edge structure 35 (XANES) spectroscopy is routinely achieved with TXM-XANES, mainly operating in the hard 36 X-ray regime (5 to 12 keV) [3–5]. Its application areas include materials science, physics, 37 chemistry, and biology. For instance, it can be used for chemical mapping in battery studies [6,7] 38 and mesoscale degradation [8]. 39

In TXM-XANES, the intensity change of each pixel is scrutinized to generate XANES spectra that are matched against reference compounds. Some common techniques, including the edge-50 or linear combination fitting (LCF) [1], are used to fit the spectra, then a two-dimensional colormap is constructed to display the chemical phase combination of each pixel. The XANES Edge-50 point (energy at 0.5 spectrum position), which measures the absorption spectra of materials within the energy range of 5 keV to 12 keV, is a widely-used method defining the

absorption edge energy. The utilization of the Edge-50 XANES technique has been progressively 46 examined for characterizing the chemical composition and structure of environmental material [9]. 47 On the other hand, [10] proposed using LCF to determine the phase composition of a chemical 48 sample from normalized XANES spectra. The XANES image at each pixel represents a spectrum 49 at a particular location, which can be fitted with reference spectra to produce spatially resolved 50 chemical state information. This technique significantly simplifies the processing and analysis 51 of XANES spectra using LCF. These traditional methods have been extensively used in the 52 literature [11–14]. Notably, Xiao et al. [15] present a workflow software integrating a few 53 valuable tools for transmission X-ray microscopy data analysis, providing rich image visualization 54 and processing routines. 55

Although traditional methods are widely applicable, they rely on high-quality TXM-XANES 56 images. A relatively slow acquisition process is needed to achieve sufficient energy resolution, 57 recording hundreds or thousands of energy points and a long exposure time. Fast TXM-XANES 58 imaging is crucial for reliably solving morphological chemical phase transitions, as in 3D battery 59 material research. To increase the speed of TXM-XANES imaging, energy points are reduced, 60 or X-ray exposure time is minimized, which is more favorable for radiation-sensitive samples, 61 similar to low-dose medical X-ray imaging applications. However, excessively short exposure 62 times can result in measurements with strong noise [16]. Furthermore, when acquiring XANES 63 data, there are many variations in the X-ray exposure conditions and inherent material properties, 64 contributing to the variability of XANES spectra [17]. In the face of strong noise and spectral 65 variability, the Edge-50 and LCT methods fail to obtain a reasonable interpretation of elemental 66 and chemical information. Despite efforts to optimize microscope hardware, the physical 67 limitations of the TXM-XANES imaging system remain challenging to overcome. To address 68 this obstacle, computational algorithm development is inevitable for improving downstream 69 analysis through fitting results. 70

Spectral unmixing methods [18] have numerous applications in imaging science, including 71 remote sensing [19–21], optical microscopy [22], and X-ray imaging [23–25]. The unmixing 72 technique aims to decompose a spectrum of mixed pixels into a set of distinct spectral signatures, 73 known as endmembers, along with their corresponding fractional abundances [26, 27]. By 74 utilizing spectral unmixing in X-ray microspectroscopy, the chemical states of materials can be 75 directly obtained, bypassing the fitting process. Various regularizations have been developed in 76 spectral unmixing methods to utilize the prior information on the abundance map against noise. 77 In addition, in the face of spectral variability, many model formulations have been proposed 78 in the unmixing problems [28–32]. The principle underlying the LCF method is essentially 79 spectral unmixing [18], whereby the mixture is analyzed by determining the contribution of the 80 reference spectra. However, it is sensitive to noise and limited in handling problems with spectral 81 variability. 82

The TXM-XANES unmixing task involving spectral variability can be formulated as an 83 optimization model. After extracting the scale factors from spectral variability in each pixel, the 84 chemical map corresponding to different chemical states can be seen as a sequence of images. 85 This allows us to utilize prior information and enhance the robustness of our model. In this study, 86 we employ two regularization techniques to achieve this goal. Firstly, the explicit regularizer 87 is applied to the reconstructed image to incorporate spatial and spectral information through 88 pixel connections in the unmixing process [33, 34], an explicit regularizer pertains to prior 89 information that is pre-defined in model-based methods. On the other hand, the Plug and Play 90 (PnP) technique utilizes state-of-the-art denoisers to tackle linear inverse problems in various 91 hyperspectral image processing tasks [35–41]. In contrast to traditional model-based methods, 92 which require explicit and manually designed image priors, PnP can implicitly establish the prior 93 information through the use of denoisers. Therefore, in the subsequent sections, we refer to PnP 94 as an implicit regularizer. The main contributions of this paper are summarized as follows: 95



Fig. 1. Framework of the proposed model for material chemical states retrieval in the form of unmixing for X-ray microspectroscopy. The normalized XANES spectra from each pixel are unmixed to create a chemical phase map  $\mathbf{X}$ , which also considers the image's scaling factor.

We present a novel and robust framework for X-ray TXM-XANES imaging, which incorporates various realistic factors that affect the spectra, such as noise and spectral variability.

Our proposed framework is evaluated extensively using both quantitative and qualitative methods on synthetic and experimental datasets. The results indicate that our proposed methods surpass the state-of-the-art. Our framework with an implicit regularization achieves the best performance.

The rest of the paper is organized as follows. In Section 2, we propose a novel data formulation
 model for the material chemical states retrieval in X-ray microspectroscopy and the corresponding
 algorithms to solve it. Section 3 presents the experimental results and subsequent discussions.
 Finally, Section 4 provides a summary and future perspectives.

#### 107 2. Proposed Robust Unmixing Framework

# 108 2.1. Model Formulation

Here the observed XANES image is represented by  $\mathbf{Y} = [\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_N] \in \mathbb{R}^{T \times N}$ , where each column vector is obtained by lexicographically ordering the TXM image with size  $N = M \times K$ , and *T* is the number of energy points. The LCF model generates the noisy measurements **Y** from the chemical phase map  $\mathbf{M} = [\mathbf{m}_1, \mathbf{m}_2, \dots, \mathbf{m}_n] \in \mathbb{R}^{L \times N}$ , pixel-wisely.

$$\mathbf{y}_k = \mathbf{A}\mathbf{m}_k + \mathbf{r}_k, \ k = 1, \dots, N,\tag{1}$$

where  $\mathbf{A} \in \mathbb{R}^{T \times L}$  is the dictionary, representing spectra of the reference materials in the XANES images, *L* is the number of materials, and the noise  $\mathbf{r}_k$  is assumed to follow Gaussian distribution. Given  $\mathbf{A} \in \mathbb{R}^{T \times L}$ , LCF is to solve a least square problem. However, this is an inverse problem which is sensitive to the noise. In addition, the chemical phase map  $\mathbf{m}_k$  is a vector with non-negative values but does not sum up to one. This is because of the illumination conditions and uncertainty in the chemical process. As a result, some critical prior information contained in  $\mathbf{m}_k$  as an image is lost, and it becomes difficult to apply certain regularization techniques.

Here, we introduce the scaling factor  $s_k$  for this pixel-wise spectral variability such that this process can be effectively modeled by approximating the chemical phase map of each pixel with

the scaled version of the reference spectra. We split the  $\mathbf{m}_k$  into two variables

$$\mathbf{m}_k = s_k \mathbf{x}_k,$$

where  $s_k$  is a scalar in the *k*-the pixel and  $\mathbf{x}_k$  is the normalized chemical phase map which has the sum-to-one property. Then the forward model (1) can be rewritten as

$$\mathbf{y}_k = s_k \mathbf{A} \mathbf{x}_k + \mathbf{r}_k, \ k = 1, \dots, N, \tag{2}$$

<sup>122</sup> In other words, we get the matrix form of (2) as

$$\mathbf{Y} = \mathbf{A}\mathbf{X}\mathrm{diag}(\mathbf{s}) + \mathbf{R},\tag{3}$$

where diag(s) represents a diagonal matrix with its diagonal values  $\mathbf{s} = [s_1, s_2, ..., s_N]^T$  and  $s_i \ge 0, \forall i \in 1, ..., N$ . The noise term is  $\mathbf{R} = [\mathbf{r}_1, \mathbf{r}_2, ..., \mathbf{r}_N]$ . Fig. 1 gives the macro diagram of spectral unmixing for the XANES imaging. With (3), we get an optimization problem:

$$\min_{\mathbf{X},\mathbf{s}} \quad \frac{1}{2} \|\mathbf{Y} - \mathbf{A}\mathbf{X}\operatorname{diag}(\mathbf{s})\|_{F}^{2}$$
s.t.  $\mathbf{X} \ge \mathbf{0}, \ \mathbf{s} \ge \mathbf{0}, \ \mathbf{1}^{T}\mathbf{X} = \mathbf{1},$ 

$$(4)$$

where  $\|\cdot\|_F$  is the Frobenius norm, i.e.,  $\|\mathbf{Z}\|_F = \sqrt{\sum z_{ij}^2}$  for any **Z**. Note that combining **X** and **s** into a nonnegative least squares problem would lose some prior information on **X** itself, especially when **X** and **s** are independent. In the following, we will utilize the prior information and propose a robust optimization framework under a low exposure time measurement.

### 130 2.2. Explicit and Implicit Regularizations

Regularization is a widely-used technique in image processing to promote sparsity in terms of certain transformations on the image [42, 43]. Here the normalized chemical phase map can be regarded as a group of images and has a piece-wise spatial correlation. Hence, we first adapt a regularization into (4) in a unified framework, and the proposed model can be expressed as follows:

$$\min_{\mathbf{X},\mathbf{s}} \quad \frac{1}{2} \|\mathbf{Y} - \mathbf{A}\mathbf{X}\operatorname{diag}(\mathbf{s})\|_{F}^{2} + \lambda \sum_{j=1}^{L} \Phi(\mathbf{x}_{j}) + I_{\Omega_{1}}(\mathbf{X}) + I_{\Omega_{2}}(\mathbf{s}),$$
(5)

where  $\Phi(\mathbf{x})$  represents a regularization term enforcing prior knowledge of  $\mathbf{x}$ . The regularization parameter is represented as  $\lambda$ . Here  $\mathbf{x}_j$  is the *j*-th row in the chemical map  $\mathbf{X}$ , and  $I_{\Omega}$  is the indicator function for the nonnegative value, i.e.,

$$I_{\Omega}(\mathbf{x}) = \begin{cases} 0 & \mathbf{x} \in \Omega, \\ +\infty & \text{otherwise.} \end{cases}$$
(6)

In addition,  $\Omega_1 = {\mathbf{X} | \mathbf{X} \ge \mathbf{0} \text{ and } \mathbf{1}^T \mathbf{X} = \mathbf{1}}$  and  $\Omega_2 = {\mathbf{s} | \mathbf{s} \ge \mathbf{0}}$ . Since the sparsity emerges in terms of certain transformations, we define  $\Phi(\mathbf{x}) = \phi_1 \circ \phi_2(\mathbf{x}) := \phi_1(\phi_2(\mathbf{x}))$  where  $\phi_1$  is the sparse term and  $\phi_2$  is certain transformations. After splitting the variables, the problem in (6) with auxiliary variables can be expressed as follows:

$$\min_{\mathbf{X},\mathbf{s}} \quad \frac{1}{2} \|\mathbf{Y} - \mathbf{A}\mathbf{M}\|_F^2 + \lambda \sum_{j=1}^L \phi_1(\mathbf{u}_j) + I_{\Omega_1}(\mathbf{W}) + I_{\Omega_2}(\mathbf{t})$$
s.t. 
$$\mathbf{M} = \mathbf{X} \operatorname{diag}(\mathbf{s}), \mathbf{u}_j = \phi_2(\mathbf{x}_j), \mathbf{W} = \mathbf{X}, \mathbf{t} = \mathbf{s}.$$

$$(7)$$

<sup>143</sup> and the augmented Lagrangian is as follows:

$$\mathcal{L}(\mathbf{X}, \mathbf{s}, \mathbf{M}, \mathbf{U}, \mathbf{W}, \mathbf{t}, \mathbf{F}) = \frac{1}{2} \|\mathbf{Y} - \mathbf{A}\mathbf{M}\|_{F}^{2} + \lambda \sum_{j=1}^{L} \phi_{1}(\mathbf{u}_{j}) + \frac{\rho}{2} \|\mathbf{X} \text{diag}(\mathbf{s}) - \mathbf{M} + \mathbf{C}\|_{F}^{2} - \frac{\rho}{2} \|\mathbf{C}\|_{F}^{2}$$
$$+ \frac{\rho}{2} \sum_{j=1}^{L} \|\phi_{2}(\mathbf{x}_{j}) - \mathbf{u}_{j} + \mathbf{d}_{j}\|_{2}^{2} - \frac{\rho}{2} \|\mathbf{d}_{j}\|_{2}^{2} + \frac{\rho}{2} \|\mathbf{X} - \mathbf{W} + \mathbf{E}\|_{F}^{2} - \frac{\rho}{2} \|\mathbf{E}\|_{F}^{2}$$
$$+ \frac{\rho}{2} \|\mathbf{s} - \mathbf{t} + \mathbf{g}\|_{2}^{2} - \frac{\rho}{2} \|\mathbf{g}\|_{2}^{2},$$
(8)

where  $\mathbf{C}$ ,  $\mathbf{D} = [\mathbf{d}_1, \mathbf{d}_2, \dots, \mathbf{d}_L]$ ,  $\mathbf{E}$ ,  $\mathbf{g}$  are dual variables and  $\lambda$ ,  $\rho$  are positive parameters. Denote  $\mathbf{F} = [\mathbf{C}; \mathbf{D}; \mathbf{E}; \text{diag}(\mathbf{g})]$ . It's worth noting that  $\lambda$  regulates the influence of the regularization term and significantly affects the unmixing results, whereas  $\rho$  is a penalty parameter in the augmented Lagrangian function and only affects the convergence speed. Now, we present two types of regularizations for this unified framework (5).

**Explicit Regularization.** We first adapt some explicit regularization in the model (5). In order 149 to promote sparsity prior to the XANES images,  $\phi_1(\cdot)$  is denoted by  $\|\cdot\|_1$ . Here we consider 150 the linear transformations  $\phi_2$  to project the image into another domain. Note that  $\|\phi_2(\mathbf{x}_i)\|_1$ 151 becomes total variation [44] if we choose  $\phi_2(\cdot)$  as a discrete gradient operator. We apply 152 the alternating direction method of multipliers (ADMM) [45] to solve this model. All these 153 variables are updated alternatively, and the sub-problems' derivation has been included in the 154 Supplement Material. Algorithm 1 summarizes the whole process for solving model (8) with 155 explicit regularization. Moreover, we further the sequence generated by Algorithm 1, which has 156 at least one accumulation point satisfying the Karush-Kuhn-Tucker (KKT) conditions [46] of (8) 157 with explicit regularization. The proof can be found in Supplementary Material. 158

**Implicit Regularization.** Designing an explicit regularizer can be challenging, as complex 159 regularizers often complicate optimization problems, making the entire process more difficult. 160 Rather than using a handcrafted regularizer, we aim to implicitly leverage prior knowledge about 161 the spectral characteristics of materials in the scene to achieve better regularized unmixing results. 162 In the implicit regularization,  $\phi_1(\cdot)$  enforces prior knowledge of **X**, while  $\phi_2(\cdot)$  represents identity 163 transformation, i.e.  $\phi_2(\mathbf{x}) = \mathbf{x}$ . All these variables are updated sequentially, and the solution to 164 the subproblem involving the variables **X** and **U**, which differs from the explicit regularization, 165 is thoroughly elucidated in the Supplementary Material. In the case of the subproblem  $\mathbf{u}_i$ , the 166  $\mathbf{u}_i$ -subproblem is to solve a proximal operator as follows: 167

$$\mathbf{u}_{j}^{k+1} = \arg\min_{\mathbf{u}} \frac{\rho}{2} ||\mathbf{u}_{j} - \mathbf{x}_{j}^{k+1} - \mathbf{d}_{j}^{k}||_{F}^{2} + \lambda \phi_{1}(\mathbf{u}_{j}).$$
(9)

We define  $\sigma = \sqrt{\lambda/\rho}$ , it is not difficult to show that (9) is

$$\mathbf{u}_{j}^{k+1} = \arg\min_{\mathbf{u}} \frac{1}{2\sigma^{2}} ||\mathbf{u}_{j} - \mathbf{x}_{j}^{k+1} - \mathbf{d}_{j}^{k}||_{F}^{2} + \phi_{1}(\mathbf{u}_{j}).$$
(10)

Treating as  $\mathbf{x}_{j}^{k+1} + \mathbf{d}_{j}^{k}$  as the "noisy" image, (10) minimizes the residue between  $\mathbf{x}_{j}^{k+1} + \mathbf{d}_{j}^{k}$  and the "clean" image  $\mathbf{u}_{j}$  using the prior  $\phi_{1}(\mathbf{u}_{j})$ , so (10) can be viewed as a standard image-denoising problem. We employ established and effective denoising operators in the PnP framework iterations, such as the conventional BM3D [47] or DnCNN [48], which utilizes deep learning. To adapt to the variation in noise during each iteration process. we increase  $\rho^{k+1} = \gamma_k \rho^k$  for  $\gamma_k \ge 1$ , it has been used in various problem [49, 50]. Incorporating it into the (9), and define  $\sigma^k = \sqrt{\lambda/\rho^k}$  is a parameter controlling the strength of the denoiser. After acquiring the necessary

- denoising operators, we update the primal and dual variables in the ADMM process, following
- 177 Algorithm 1.

Algorithm 1: The Framework for TXM-XANES Image Unmixing with Explicit Regular-								
izer and Implicit Regularizer (denoted as RUMex and RUMim, respectively).								
Input: A TXM-XANES image Y, Dictionary A.								
Output: Phase map X, Scaling factor s.								
1: Initialize: <b>X</b> and <b>s</b> and choose parameter $\rho$ , $\lambda$ and $\gamma$ .								
2: while not converged or iterations are not reached do								
3: X is updated by								
$\begin{cases} ((\mathbf{M} - \mathbf{C})\operatorname{diag}(\mathbf{s}) + \sum_{j=1}^{L} \phi_{j}^{T}(\mathbf{u}_{j} - \mathbf{d}_{j}) + \mathbf{W} - \mathbf{E})(\operatorname{diag}(\mathbf{s})^{2} - \Delta + \mathbf{I})^{-1} & \text{for RUM}_{ex} \end{cases}$	,							
$\left( ((\mathbf{M} - \mathbf{C})\operatorname{diag}(\mathbf{s}) + \sum_{j=1}^{L} (\mathbf{u}_j - \mathbf{d}_j) + \mathbf{W} - \mathbf{E})(\operatorname{diag}(\mathbf{s})^2 + 2\mathbf{I})^{-1} \right) \text{ for RUM}_{\text{im}},$								
4: Normalize X such that $1^T \mathbf{X} = 1$ ,								
5: $\mathbf{s} \leftarrow (\mathbf{X}^T \mathbf{X} + \mathbf{I})^{-1} (\mathbf{X}^T (\mathbf{M} - \mathbf{C}) + \mathbf{t} - \mathbf{g}),$								
6: $\mathbf{M} \leftarrow (\mathbf{A}^T \mathbf{A} + \rho \mathbf{I})^{-1} (\mathbf{A}^T \mathbf{Y} + \rho \mathbf{X} \operatorname{diag}(\mathbf{s}) + \rho \mathbf{C}),$								
7. If $(\phi_2(\mathbf{x}_j) + \mathbf{d}_j, \frac{\lambda}{\rho})$ , for RUM <sub>ex</sub>								
<b>Denoiser</b> $(\mathbf{x}_j + \mathbf{d}_j, \frac{\lambda}{\alpha})$ , for RUM <sub>im</sub>								
8: $\rho \leftarrow \gamma \rho$ for RUM <sub>im</sub>								
9: $\mathbf{W} \leftarrow \max(\mathbf{X} + \mathbf{E}, 0),$								
10: $\mathbf{t} \leftarrow \max(\mathbf{s} + \mathbf{g}, 0),$								
11: $\mathbf{C} \leftarrow \mathbf{C} + \mathbf{X} \operatorname{diag}(\mathbf{s}) - \mathbf{M},$								
12: $\mathbf{d}_j \leftarrow \begin{cases} \mathbf{d}_j + \phi_2(\mathbf{x}_j) - \mathbf{u}_j, & \text{for RUM}_{\text{ex}} \\ \mathbf{d}_j + \mathbf{x}_j - \mathbf{u}_j, & \text{for RUM}_{\text{im}} \end{cases}$								
13: $\mathbf{E} \leftarrow \mathbf{E} + \mathbf{X} - \mathbf{W},$								
14: $\mathbf{g} \leftarrow \mathbf{g} + \mathbf{s} - \mathbf{t}$ .								
15: end while								

**Remark 1** Dictionary selection: The proposed algorithm can quickly and accurately extract the spectral signal from the XANES imaging data. However, the reference spectra are a critical component for achieving optimal performance. When the reference spectra are unknown, we use the conventional spectra extraction method, which is the vertex component analysis (VCA) [51] as a baseline for dictionary identification. In the real data analysis in Section 3.3, we demonstrate that using VCA with denoising results in more accurate reference spectra extraction, particularly in strong-noise environments.

### **3.** Experiments and Results

In this section, we will evaluate the performance of the proposed methods quantitatively and visually on both synthetic and actual datasets. Regarding the comparison with different priors, our methods are divided into two groups: the explicit regularization (RUM<sub>ex</sub> denoted as total variation) and implicit regularization (RUM<sub>im</sub> denotes as PnP with BM3D [47]). More results on different regularizers and the algorithm behaviors can be found in the Supplementary Material. These proposed methods will be assessed compared to the traditional methods, namely Edge-50 and LCF.

### <sup>194</sup> 3.1. Experimental Settings and Evaluation Metrics

Data Description. The dataset presented in Fig. 2 comprises three X-ray projection images
 (Particles, Polymer, and Round) and three reconstructed slices (Wedge, Electrode, and Brine),



Fig. 2. Left: Typical examples of the test datasets: projections and reconstructed slices; Right: Normalized spectra under different Ni valence states of X-ray XANES in a battery cathode. State 1, 2, 3, 4, and 5 represent Ni's different valence states.

which are utilized to create a simulation of 2D and 3D TXM-XANES imaging scenarios. To generate simulated movie data, as shown in Fig. 2, the reference spectra of different Ni valence states are randomly assigned to pixels in the images for various phase maps. The sample is assumed to contain various valence states of Ni elements, and the proportion of Ni elements satisfies the sum-to-one constraint. We describe the state using number (1, 2, 3, ..., L).

Evaluation Metrics. Each synthetic dataset frame is further corrupted with additive Gaussian noise with varying noise levels, with the standard deviation  $\sigma \in [1, 7]$ . For the performance

<sup>203</sup> noise with varying noise levels, with the standard deviation  $\sigma \in [1, 7]$ . For the performance <sup>204</sup> assessment of the algorithms, we utilize two commonly used criteria to measure the accuracy of

the phase map: the peak signal-to-noise ratio (PSNR) and the structural similarity index (SSIM).

<sup>206</sup> PSNR is defined as follows:

$$PSNR = 20 \times \log_{10} (MAX/RMSE),$$
(11)

where MAX is the maximum pixel value of the estimated image  $\hat{\mathbf{X}}$  across all pixels, and RMSE

is the root mean square error between  $\hat{\mathbf{X}}$  and the ground truth  $\mathbf{X}$ . The RMSE is defined as:

RMSE = 
$$\sqrt{\frac{1}{n_1 n_2} \sum_{i=1}^{n_1} \sum_{l=1}^{n_2} \|\hat{x}(i,l) - x(i,l)\|^2},$$
 (12)

where  $n_1$  and  $n_2$  are the number of rows and columns in the image **X**. We use the estimated phase map  $\hat{\mathbf{X}}$  and the ground truth **X** to calculate PSNR. Then PSNR is calculated by the average of the PSNR of each chemical phase map.

SSIM is a metric that quantifies the similarity between two images, which is calculated by the average of the SSIM of each chemical phase map. The SSIM formula is expressed as follows:

SSIM(
$$\hat{\mathbf{X}}, \mathbf{X}$$
) =  $\frac{[(2\mu_{\hat{\mathbf{X}}}\mu_{\mathbf{X}} + c_1) * (2\sigma_{\hat{\mathbf{X}}\mathbf{X}} + c_2)]}{[(\mu_{\hat{\mathbf{X}}}^2 + \mu_{\mathbf{X}}^2 + c_1) * (\sigma_{\hat{\mathbf{X}}}^2 + \sigma_{\mathbf{X}}^2 + c_2)]},$  (13)

where  $\mu_{\hat{\mathbf{X}}}$  and  $\mu_{\mathbf{X}}$  represent the means of  $\hat{\mathbf{X}}$  and  $\mathbf{X}$ , respectively.  $\sigma_{\hat{\mathbf{X}}}$  and  $\sigma_{\mathbf{X}}$  denote the standard deviations of  $\hat{\mathbf{X}}$  and  $\mathbf{X}$ , respectively.  $\sigma_{\hat{\mathbf{X}}\mathbf{X}}$  is the covariance of  $\hat{\mathbf{X}}$  and  $\mathbf{X}$ , while  $c_1$  and  $c_2$  are small constants added to prevent division by zero errors and stabilize the formula.

## 217 3.2. Results of Synthetic Datasets

<sup>218</sup> **Different Noise Levels**. In this simulation scenario, we assume that each of the six simulated <sup>219</sup> movie image datasets exclusively contains two Ni elements, namely, state 1 and state 2 under



Fig. 3. A visual comparison of the chemical phase map for various methods on the Round data under different noise levels ( $\sigma = 3$  on the top and  $\sigma = 7$  on the bottom). Note that the other chemical map is the reverse since L = 2.

Table 1. Comparison of PSNR (dB) and SSIM in for six simulated datasets using different approaches and noise levels ( $\sigma$  is from 1 to 7).

Test set	σ	Edge-50		LCF		RUM <sub>ex</sub>		RUM <sub>im</sub>	
		PSNR	SSIM	PSNR	SSIM	PSNR	SSIM	PSNR	SSIM
Particle	1	8.98	0.10	16.11	0.57	38.22	0.94	42.65	0.98
	3	5.96	0.08	9.33	0.28	32.64	0.87	37.36	0.96
	5	5.73	0.07	6.80	0.22	29.59	0.76	34.39	0.93
	7	5.71	0.07	5.26	0.20	27.63	0.69	31.39	0.87
Electrodo	1	9.19	0.23	17.37	0.51	42.39	0.95	46.79	0.99
	3	6.23	0.22	10.00	0.36	38.38	0.92	42.27	0.98
Liccubac	5	6.01	0.22	7.29	0.35	33.65	0.83	37.97	0.95
	7	5.97	0.21	6.03	0.36	31.51	0.78	35.21	0.92
	1	11.20	0.23	19.94	0.59	42.36	0.95	47.10	0.99
Polymer	3	6.56	0.22	11.86	0.39	37.85	0.89	42.74	0.98
Tolymer	5	6.07	0.21	8.94	0.35	32.44	0.75	38.53	0.94
	7	5.97	0.21	7.27	0.35	30.00	0.68	34.29	0.86
	1	10.04	0.23	19.23	0.56	47.26	0.99	51.01	1.00
Wedge	3	6.58	0.21	10.97	0.35	38.98	0.93	43.35	0.99
Wedge	5	6.23	0.21	8.15	0.34	33.65	0.83	38.14	0.95
	7	6.13	0.21	6.88	0.32	31.41	SSIM 0.94 0.87 0.76 0.69 0.95 0.92 0.83 0.78 0.95 0.89 0.75 0.68 0.99 0.75 0.68 0.99 0.75 0.68 0.99 0.93 0.76 0.92 0.80 0.70 0.63 0.92 0.83 0.92 0.83 0.66 0.92	34.86	0.89
	1	7.06	0.04	12.17	0.50	35.28	0.92	39.58	0.97
Round	3	4.89	0.01	6.81	0.28	28.53	0.80	34.14	0.94
Round	5	4.66	0.01	5.06	0.22	26.35	0.70	30.78	0.88
	7	4.63	0.01	3.95	0.19	24.43	0.63	28.19	0.80
Brine	1	10.46	0.03	19.86	0.52	40.34	0.92	45.40	0.97
	3	4.96	0.01	10.54	0.24	35.59	0.83	39.85	0.94
	5	4.59	0.01	7.08	0.18	30.90	0.66	37.01	0.91
	7	4.55	0.01	5.17	0.17	28.52	0.56	33.00	0.80

different noise levels. This configuration results in a dictionary composed of two reference 220 spectra. Consequently, the generated chemical maps illustrate the relative proportions of states 221 1 and 2, within the chemical material. To enhance clarity, when presenting these phase maps, 222 each map distinctly portrays the proportion of one Ni element. This approach aligns with the 223 constraint that the Ni element proportions collectively sum to one. In the case where L = 2. 224 the second phase map showcases the inverse proportions of the elements. Table 1 displays the 225 performance of both traditional methods and our proposed unmixing methods incorporating 226 explicit and implicit regularizers with two reference spectra. The optimal results are highlighted 227 in bold font. Overall, both of our methods outperform traditional techniques across all datasets. 228 We observed approximately two times improvement in terms of PSNR compared to Edge-50, and 229 about one time improvement compared to LCF. Our models exhibit remarkable robustness to 230 a wide range of noise levels, particularly when the noise is substantial, as the chemical map is 231 still reconstructed effectively. RUM<sub>im</sub> improves RUM<sub>ex</sub> by up to 2 dB in terms of PSNR and 0.1 232 in terms of SSIM under all noise conditions. However, the computational cost is much heavier 233 than  $RUM_{ex}$ ; See Supplementary Material. In Fig. 3, we compare the chemical phase maps 234 of Round data obtained from various approaches under two kinds of noise levels. Except for 235 Edge-50, we observe that the estimated phase maps are consistent with the ground truth (GT). 236 However, under strong noise, our proposed methods yield less noisy phase maps closer to GT and 237 preserve the image details. The Edge-50 and LCF methods are pixel-based and do not consider 238 the spatial-spectral correlations in XANES images. Our proposed RUMex method employs fixed 239 regularizers and lacks flexibility, while the PnP framework models priors using denoiser, thus 240

eliminating the need for handcrafted regularizers.

Test set	L	LCF		RUI	M <sub>ex</sub>	RUM <sub>im</sub>	
		PSNR	SSIM	PSNR	SSIM	PSNR	SSIM
Particle	3	13.46	0.52	22.56	0.80	22.64	0.92
	4	13.36	0.48	20.32	0.73	21.23	0.85
	5	13.72	0.48	21.31	0.76	19.45	0.89
Wedge	3	11.47	0.27	24.55	0.74	26.23	0.92
	4	10.66	0.24	18.05	0.61	19.34	0.75
	5	12.62	0.25	19.26	0.66	20.13	0.80

Table 2. Comparison of PSNR (dB) and SSIM using different approaches with varying numbers of the reference spectra (the noise level  $\sigma$  is set as 3).

241

Number of Reference Spectra. To evaluate the capability of unmixing multiple spectra for 242 XANES data, we generated two datasets at reference spectra (L = 3, 4, 5) when  $\sigma = 3$ . Here, 243 different reference spectra represent different valence states of Ni, the phase map represents the 244 proportions of different Ni valence states within the chemical material. The results of PSNRs 245 and SSIMs are presented in Table 2, demonstrating our proposed framework's robustness and 246 superiority. Note that RUM<sub>im</sub> outperforms RUM<sub>ex</sub> in most of the cases but the gap becomes 247 smaller when there are more reference spectra. Additionally, Fig. 4 displays the phase maps of 248 three reference spectra (Ni valence state 1, 2, 3, respectively.) using Wedge data, the three-phase 249 maps respectively represent the proportions of state 1, 2, 3 within the Wedge, indicating that our 250 phase maps are closer to GT. Furthermore, Fig. 5 shows the result with the number of reference 251 spectra being 5 (Ni valence state 1, 2, 3, 4, 5, respectively), the five-phase maps respectively 252 represent the proportions of state 1, 2, 3, 4 and 5 within the Particle. The phase maps with Particle 253 data for Ni valence states 1, 2, and 5 obtained RUM method exhibit clearer structural details. 254



Fig. 4. The visual comparison for the chemical phase maps of the various methods on Wedge data under three reference spectra ( $\sigma = 3$ ). From top to bottom: Ni valence state 1, 2, 3, respectively.

However, the structure of the phase map for Ni valence states 3 and 4 is unclear, suggesting a
strong correlation between its reference spectra, and strongly correlated spectra may provide
similar information, making it difficult to accurately distinguish between different components.
Nevertheless, RUM<sub>im</sub> still outperforms other methods in unmixing multiple spectra.

The algorithm 1 framework is based on ADMM which decouples the forward model and the prior model terms in the optimization procedure. Mathematically, implicit regularization is designed to impose smoothness in the solution by penalizing the rate of change. In contrast, explicit regularization directly constrains the solution space, potentially leading to a more restrictive optimization landscape and may not accommodate the complexities of real-world data as effectively.

## 265 3.3. Results of Real Dataset

We apply the proposed  $RUM_{ex}$  and  $RUM_{im}$  methods to unmix real TXM-XANES data. The 266 data comprises an image of numerous Nickel-Cobalt-Manganese (NCM) particles on a charged 267 cathode, as shown on the left in Fig. 6. NCM particles were collected from 8180 eV to 8562 268 eV with varying energy intervals across the Ni K-edge, with spectral sampling of 0.5 eV in the 269 immediate edge region. The zone plate was adjusted to maintain focus. NCM particles were 270 recorded at each energy within 0.5 seconds of the sample image to account for changes in flux 271 and small beam instabilities. The (fully automated) two-dimensional XANES measurement 272 of a single field of view (FOV) can be accomplished within several minutes. Further time 273 reduction can be achieved by limiting the number of energy points to the minimum necessary 274 to discriminate different chemical phases, which, in turn, requires a priori knowledge of the 275 chemical phases present in the sample. The two chemical phases present (different Ni states) 276 were fit to XANES spectra of pure Ni. 277

The NCM particle data exhibits an extremely low signal-to-noise ratio, making it challenging to discern the reference spectra of Ni elements in the range of 8180 eV to 8562 eV under



Fig. 5. The visual comparison for the chemical phase maps of the various methods on Particle data under five reference spectra ( $\sigma = 3$ ). From left to right: Ni valence state 1, 2, 3, 4, 5, respectively.



Fig. 6. Low SNR projection image of TXM-XANES recording (left) and the reference spectra dictionary (right).



Fig. 7. The visual comparison for the chemical phase map of the various methods on NCM particle under two reference spectra (Ref#1 and Ref#2).

practical conditions. Consequently, we can only determine that it contains Ni at different internal 280 states, similar to the blind unmixing. In order to tackle this challenge, we applied a denoising 281 algorithm [16] to improve the projection images' signal-to-noise ratio (SNR). Following that, 282 we employed the VCA algorithm [51] for dictionary extraction. Figure 6 on the right-hand side 283 illustrates the two reference spectra for the two Ni states extracted by VCA [51] within the range 284 of 8180 eV to 8562 eV. Despite the presence of noise in these extracted reference spectra, our 285 method showcases resilience when working with noisy data. These techniques allowed us to 286 overcome the low SNR and extract valuable information from the NCM particle data. 287

As shown in Fig. 7, the presented RUM algorithm adeptly discerns the relative proportions 288 of the two Ni elements within the NCM particle structure. In real-world applications, it is 289 customary to employ a linear transformation on the chemical maps that depict the proportions 290 of these Ni elements. This transformation is guided by the absorption edge energies linked to 291 the two reference spectra. The detailed chemical phase map is available in the Supplementary 292 Material. Note that RUM<sub>ex</sub> has some theoretical guarantee on the convergence while the RUM<sub>im</sub> 293 shows better unmixing results in the synthetic experiments. On the other hand, due to the high 294 noise levels in each projection image of NCM particles, the chemical phase map obtained using 295 Edge-50 and LCF fails to provide any meaningful information. Our methods simultaneously 296 unmix and denoise the chemical imaging data, avoiding the accumulated error if we split these 297 two processes. Additionally, the chemical phase map of NCM particles indicates an uneven 298 reaction of the battery electrode, with some particles exhibiting a higher Ni valence state and 299 others showing a lower Ni valence state. A major reason is that during the charge and discharge 300 cycles of the battery, nickel ions undergo redox reactions and change between different Ni valence 301 states [52,53]. The utilization of the RUM unmixing method opens up avenues for enhanced 302 understanding of spatiotemporally electrochemical reactions, enabling more profound insights 303 and facilitating the optimization of composite electrode designs. 304

#### 305 4. Conclusion

This paper introduced a robust spectra unmixing framework to extract the chemical phase 306 map signal for the widely-used X-ray imaging technique. Our proposed framework considered 307 variance in spectra and maximized the use of spatial-spectral priors in X-ray microspectroscopy. 308 It outperforms traditional methods significantly when dealing with strong noise and spectral 309 variability. Experimental results showcase substantial improvements when compared to traditional 310 methods, with enhancements of up to 151.84% in PSNR and 136.33% in SSIM in simulated 311 datasets. Additionally, the framework exhibits favorable convergence properties for the explicit 312 regularization, while the implicit regularization performs better. Our future research involves 313 extending the applicability of our model to scenarios with Poisson noise and practical applications 314 where there is a strong correlation among reference spectral signatures. Another direction for 315 our future work is to develop deep learning approaches by adapting the techniques in the 3D 316

chemical imaging reconstruction [54, 55]. Moreover, the denoising operator utilized in our

<sup>318</sup> proposed method is not limited to DnCNN. We have the flexibility to leverage more advanced

denoising neural networks, including FFDNet [56] and Swin-transformer [57], to further elevate

the unmixing performance for X-ray microspectroscopy.

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**Data Availability.** Data underlying the results presented in this paper are not publicly available at this time but may be obtained from the authors upon reasonable request.

327 Supplemental document. See Supplement 1 for supporting content.

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