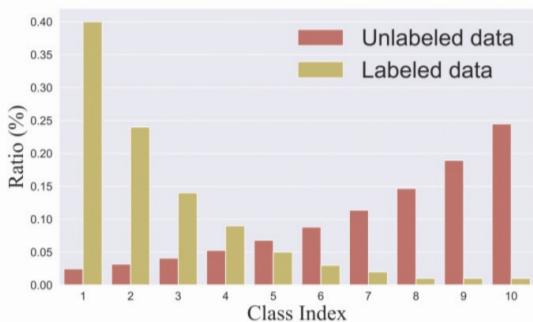
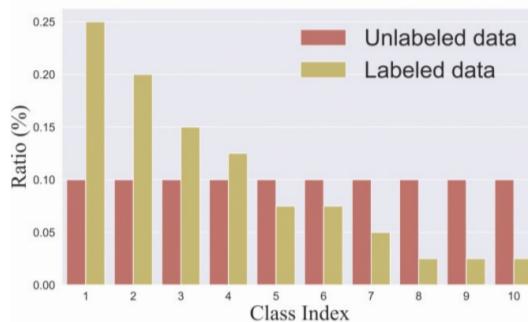


# RDA: Reciprocal Distribution Alignment for Robust SSL (ECCV 2022)

confidence threshold → fixed threshold X  
 hyperparameter-free ↓  
 dynamically adjust complicated X

distribution alignment (DA) → "labeled and unlabeled share the same distribution"

( DA scales the predictions on unlabeled data by prior information about labeled data)



Mismatched distribution



relax the assumption about the class distribution of unlabeled

RDA

maximize the mutual information between the prediction and input data

$$I(y; x) = \underbrace{H(\mathbb{E}_x [P(y|x)])}_{\substack{\uparrow \\ \text{entropy}}} - \underbrace{\mathbb{E}_x [H(P(y|x))]}_{\substack{\uparrow \\ \text{prediction}}} \quad \text{input data}$$

maximize

# Eq (1)

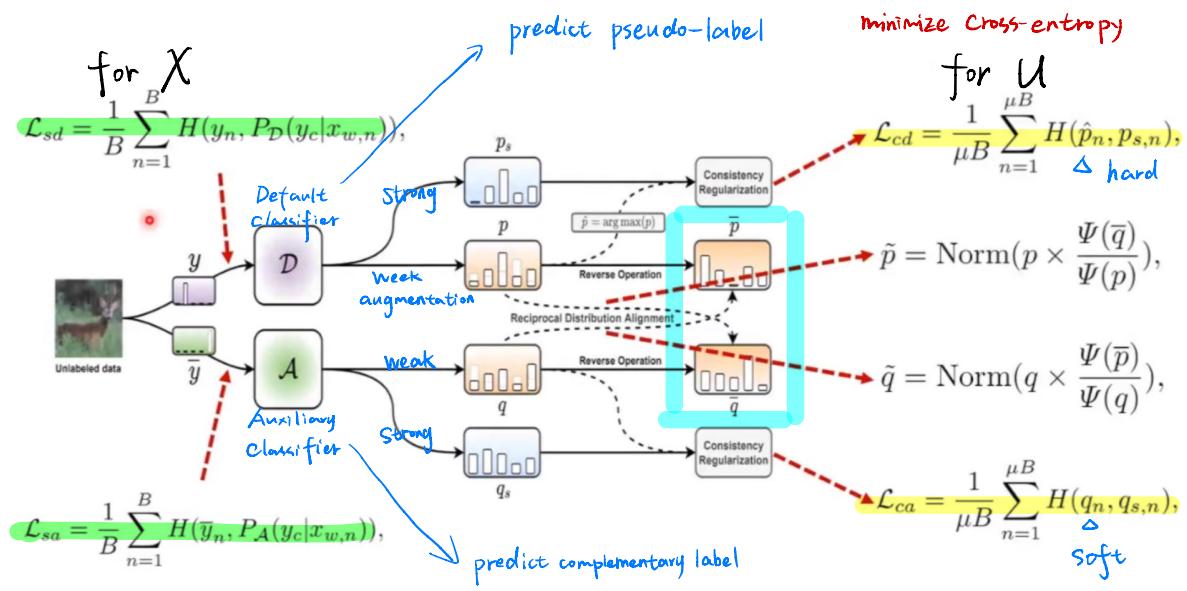
Labeled  $X = \{x_b, y_b\}_{b=1}^B$ , Unlabeled  $U = \{u_b\}_{b=1}^{\mu B}$  in a batch

$y \in Y = \{1, \dots, n\}$ : ground-truth label of  $x$

$\bar{y} \in Y \setminus \{y\}$ : complementary label of  $x$  (randomly selected)

$u_w/u_s$ : weakly/strongly augmented image for the same unlabeled  $u$

$$\left. \begin{array}{l} p = P_D(y_c|u_w) \\ p_s = P_D(y_c|u_s) \end{array} \right\} \text{pseudo-label} \quad \left. \begin{array}{l} q = P_A(y_c|u_w) \\ q_s = P_A(y_c|u_s) \end{array} \right\} \text{complementary label}$$



$$DA \rightarrow \max_{\mathcal{D}} \mathcal{H} [\mathbb{E}_u (P_D(y_c|u_w))] \quad \& \quad \max_{\mathcal{A}} \mathcal{H} [\mathbb{E}_u (P_A(y_c|u_w))]$$



Uniform prediction  $X$

[2] shows making one distribution approach to another can achieve the purpose of maximizing Eq. (1)

$$\max_{D, A} h(D, A) = \mathcal{H}(\mathbb{E}_{\text{u}}(p)) + \mathcal{H}(\mathbb{E}_{\text{u}}(q)).$$

Mismatched  $\rightarrow$  labeled distribution cannot be directly used.

distribution of class prediction  $\downarrow$   
use  $\mathbb{E}_{\text{u}}^{\uparrow}(p), \mathbb{E}_{\text{u}}(q)$  build a reciprocal alignment  
complementary

$\bar{q} = \text{Norm}(1 - q)$ ,  $\text{Norm}(x)$  is the normalized operation  $x_i' = x_i / \sum_{j=1}^n x_j$

$$\begin{aligned} \mathbb{E}_{\text{u}}(p) &\rightarrow \mathbb{E}_{\text{u}}(\bar{q}) \\ \mathbb{E}_{\text{u}}(q) &\rightarrow \mathbb{E}_{\text{u}}(\bar{p}) \end{aligned} \quad \left| \begin{array}{l} \hat{p} = \text{Norm}(p \times \frac{\psi(\bar{q})}{\psi(p)}) \\ \hat{q} = \text{Norm}(q \times \frac{\psi(\bar{p})}{\psi(q)}) \end{array} \right. \quad \begin{array}{l} \bar{i} \in (1, \dots, n) \\ \psi(\cdot) = \text{moving average over last 10 batches} \end{array}$$

aligned probability distribution

Finally, just replace  $\hat{p}_n$  with  $\hat{\hat{p}}_n$  in  $\mathcal{L}_{\text{cd}}$   
 $\hat{q}_n$  with  $\hat{\hat{q}}_n$  in  $\mathcal{L}_{\text{ca}}$